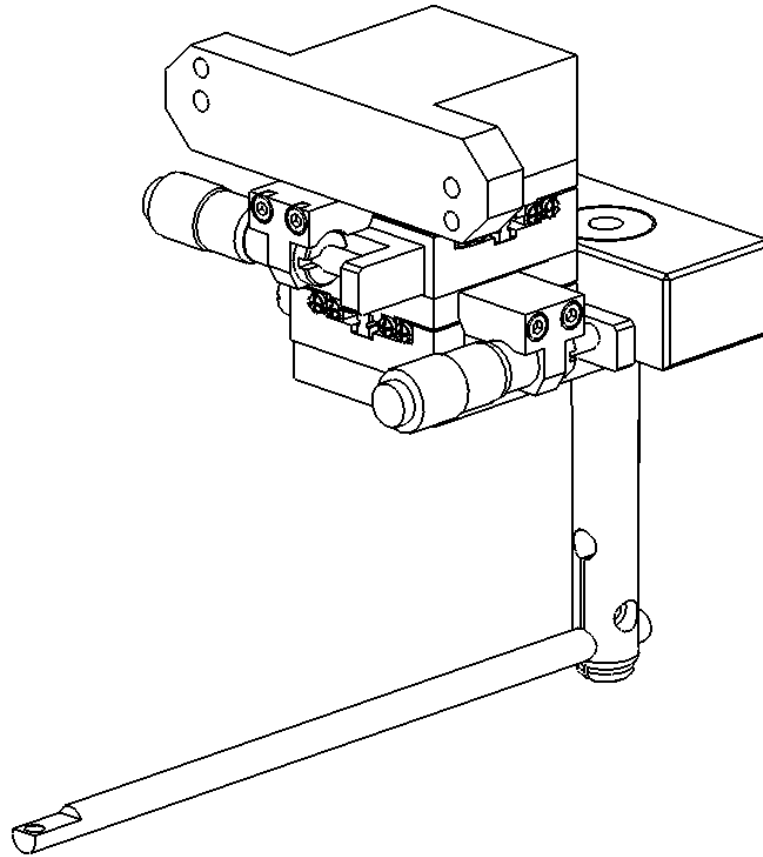


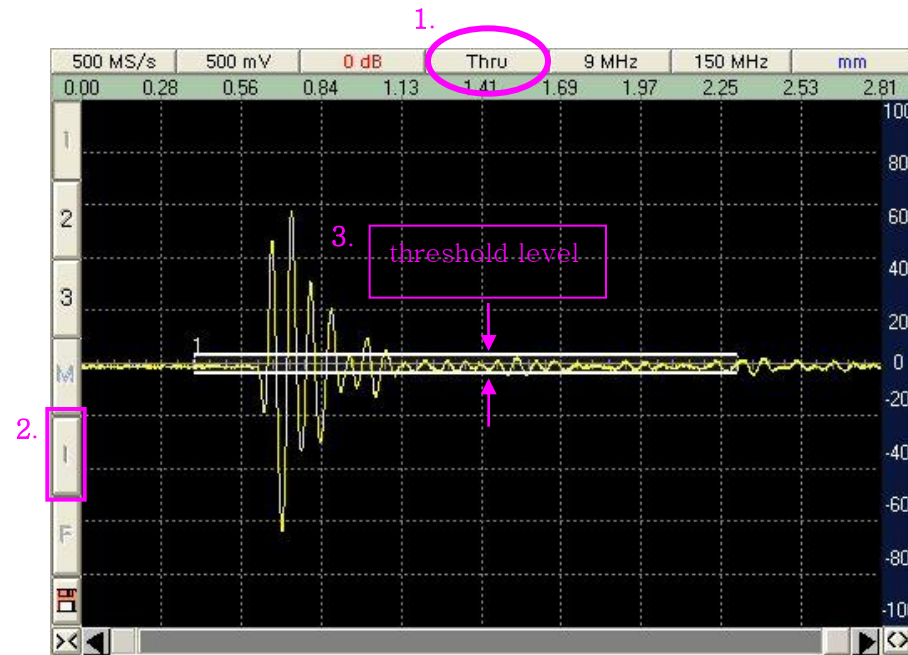


## T Scan Receiver Holder Manual





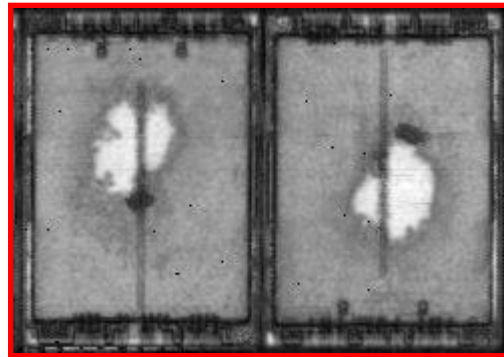
## 1. T-Scan Set in S/W



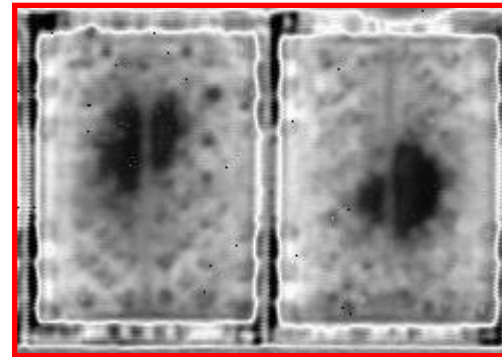
1. Change the mode to Receiver mode
2. Do not turn on the Interface Gate
3. Set the Data Gate and Threshold level as small as possible(Less than 5%)
4. Start to scan



## 2. C-Scan & T-Scan IMAGES



[Echo mode]



[Thru mode]

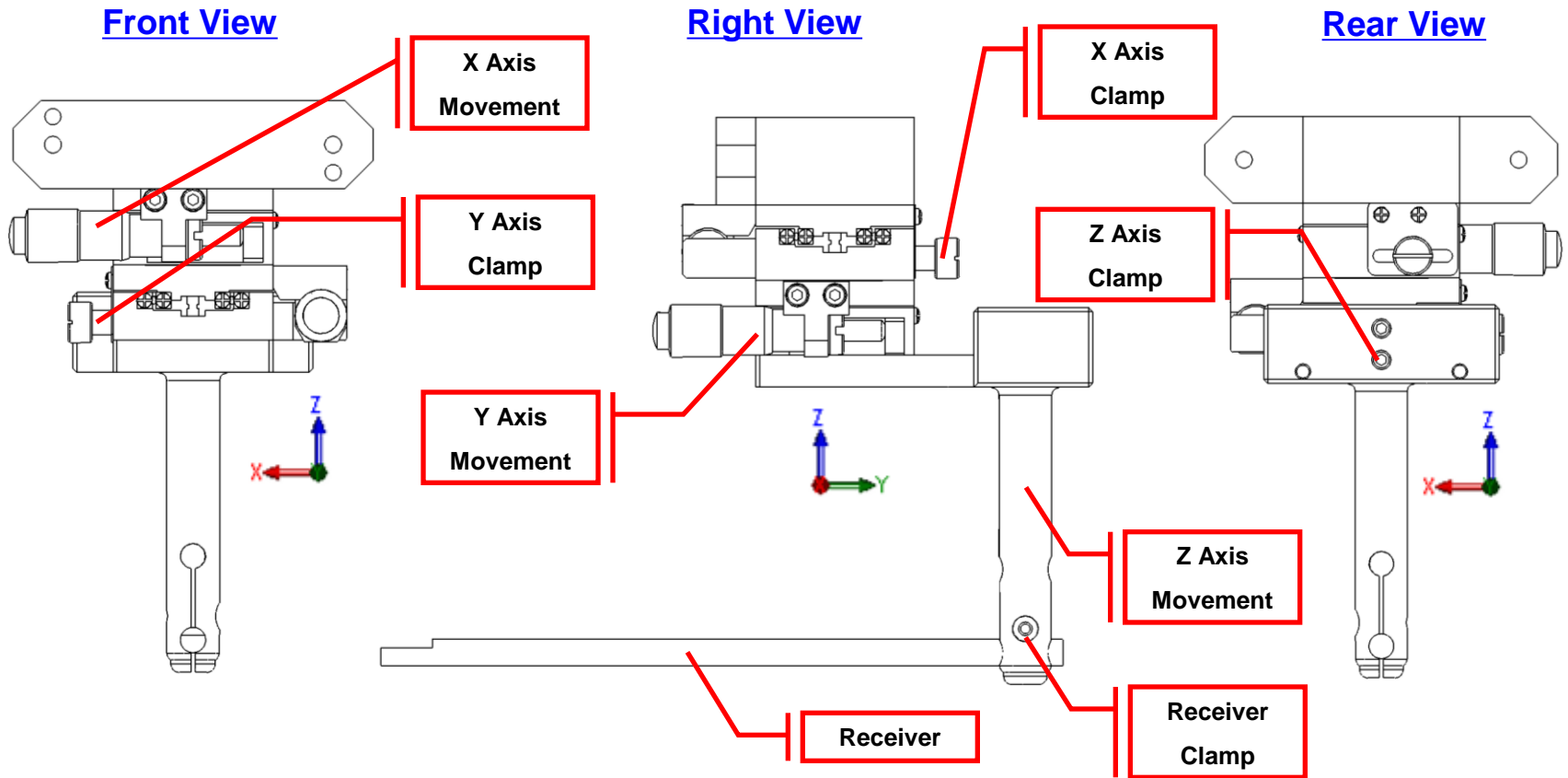
### Note

Echo mode – White part is defective part

Thru mode – Black part is defective part



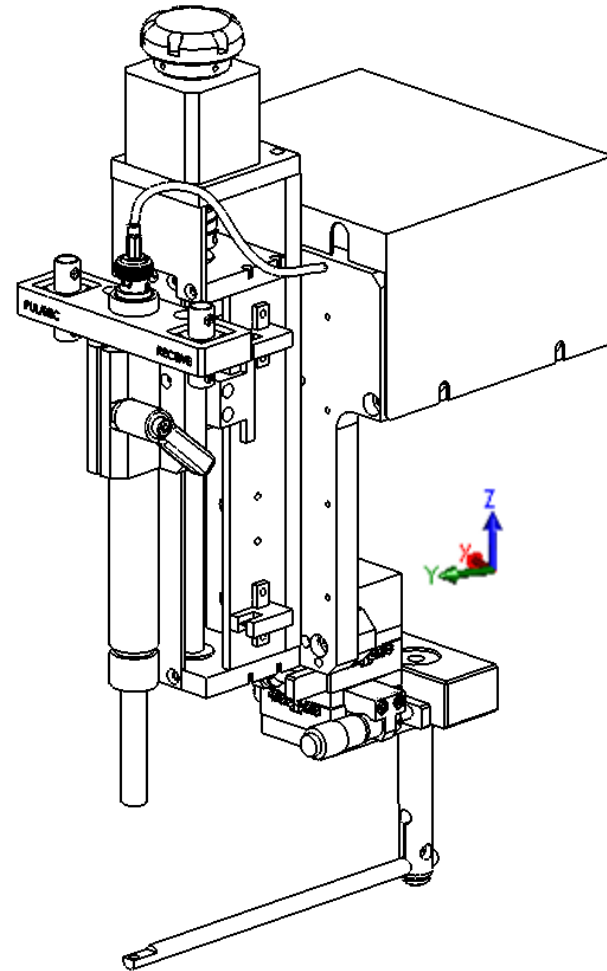
## 3. Configuration





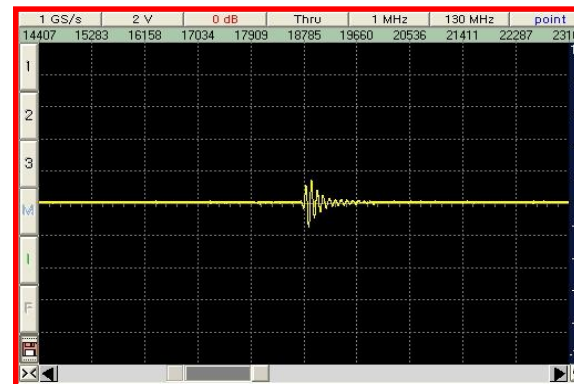
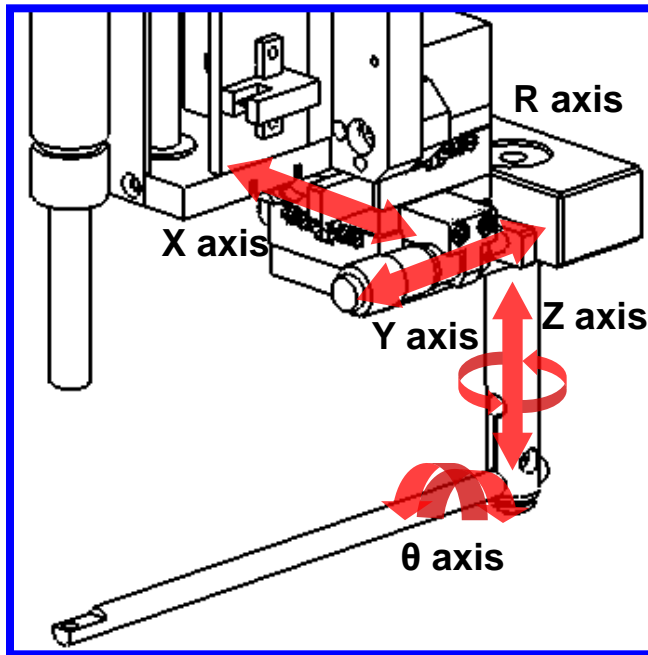
## 4. Assembly

1. Assemble Z axis ass'y and T scan ass'y
2. Fix Search Tube and Receiver in collinearity.
3. Set the rotate of X, Y, Z and  $\theta$ , and fix.





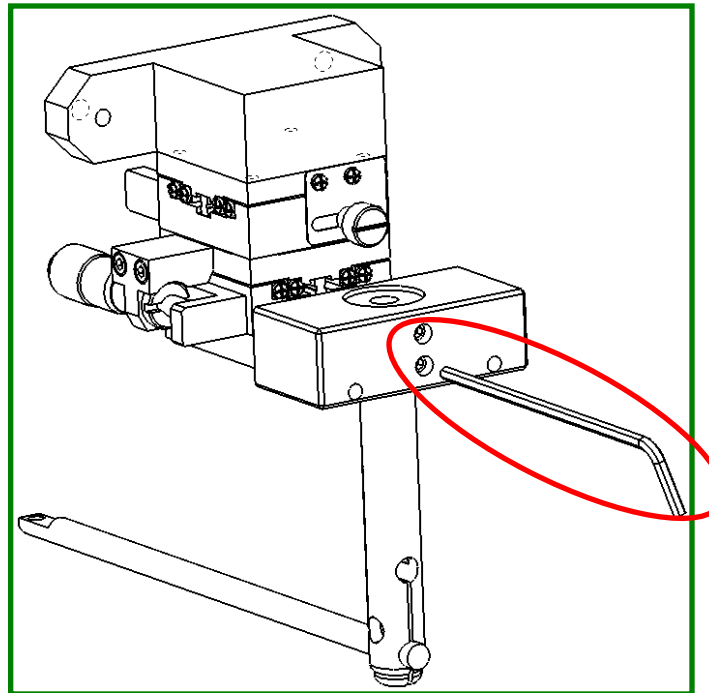
## 5. Method



Rf.- Direction of Receiver axis & A scan window



## 5.1 Method



Use it when you adjust the direction of Z axis and Rotate.

Be careful of the collision with Loading Plate while adjusting the direction.

Adjust two Clamp bolt by using the tool.

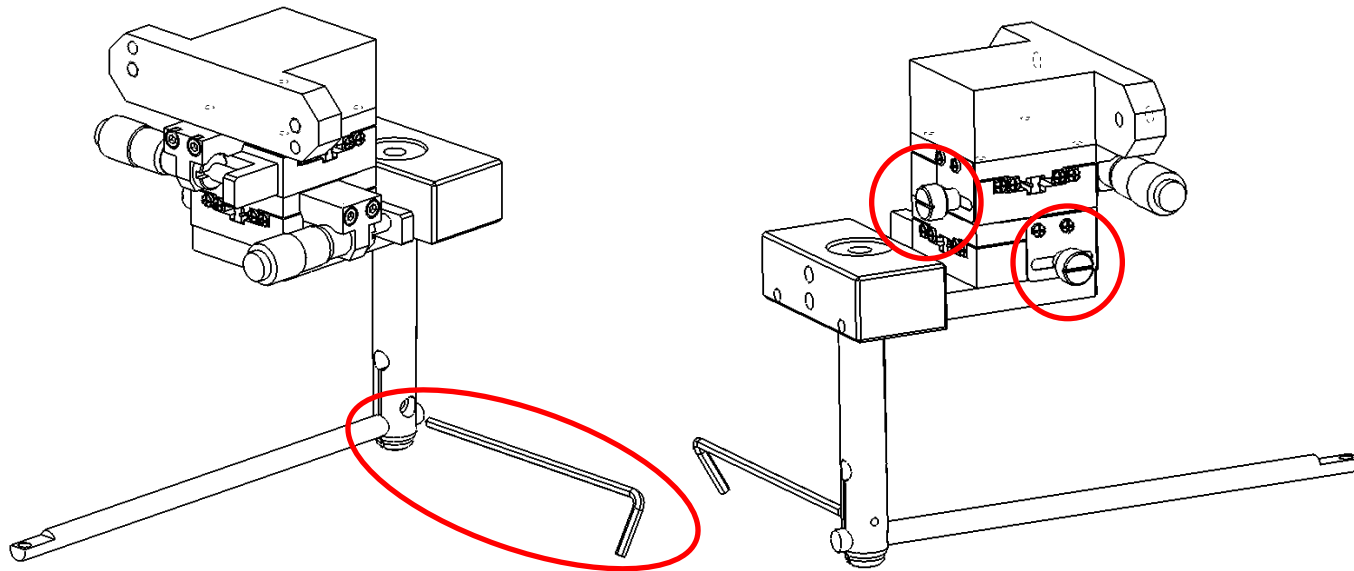
**\*\*\*Adjust only in case of the receiver transformed by external impact.\*\*\***

**Activate only after checking it as the manual after adjusting.**

**(Equipment that has the Auto Loading device is at risk of collision.)**



## 5.2 Method

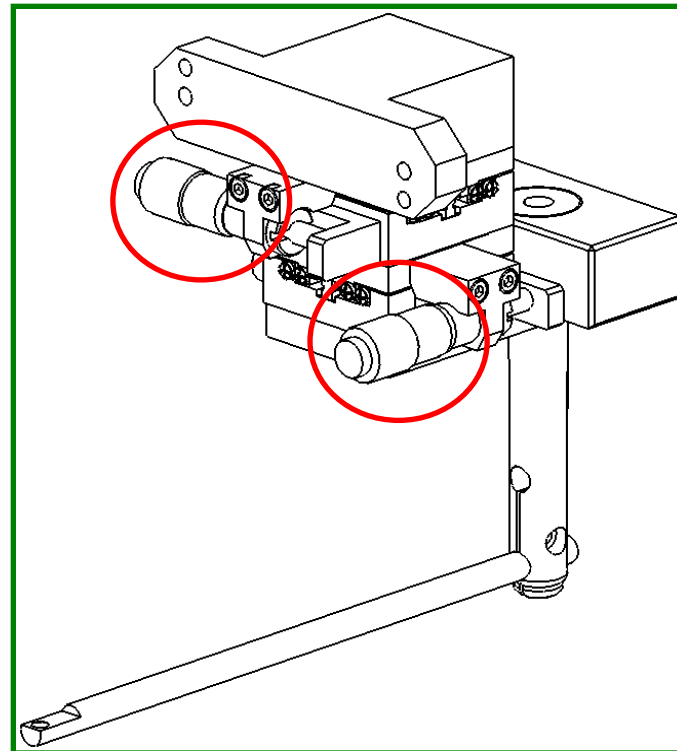


**Loosen all of the fastener anticlockwise with the tool and your hands.**





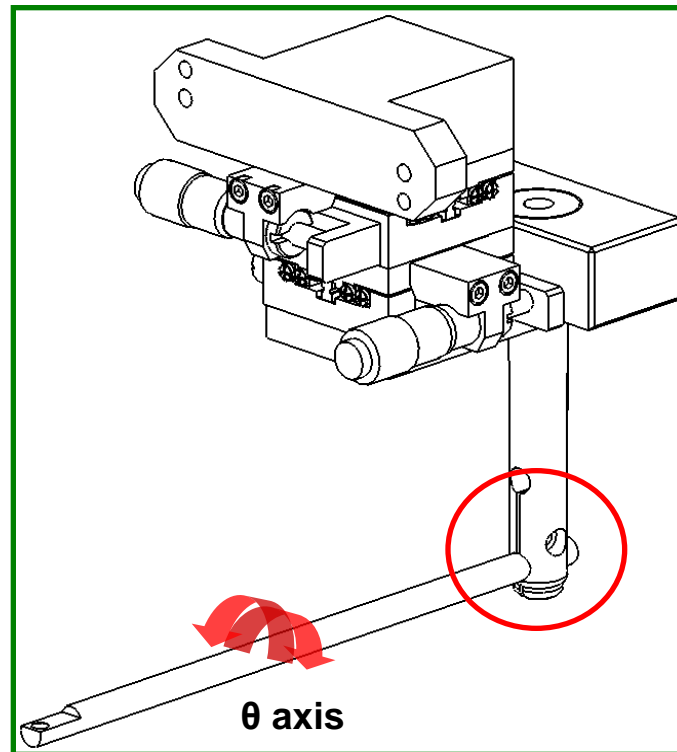
## 5.3 Method



Turn the head of X / Y axis until the highest signal is shown on the screen of A scan window.



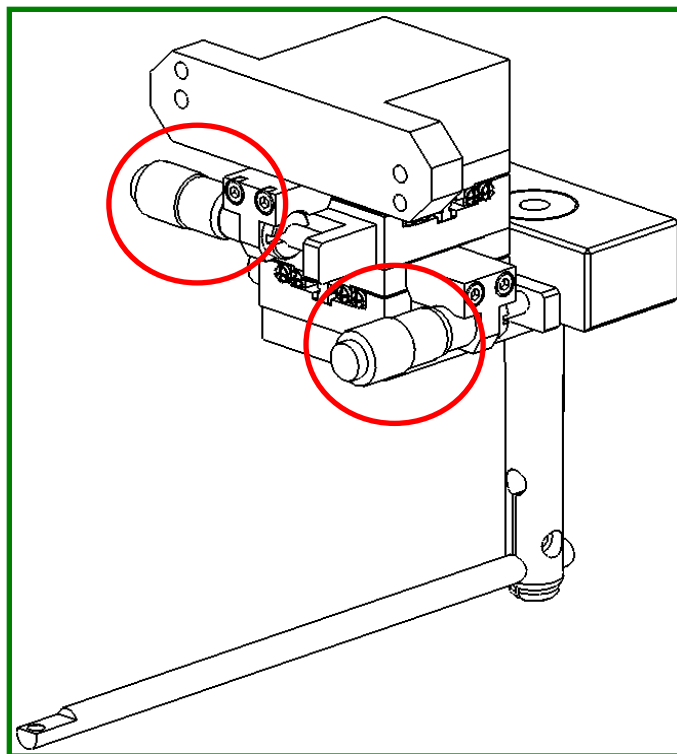
## 5.4 Method



Loosen both sides of receiver clamp bolt and turn the receiver sensor ( $\theta$  axis) until the highest signal is shown on the screen of A scan window, then fix the bolt.



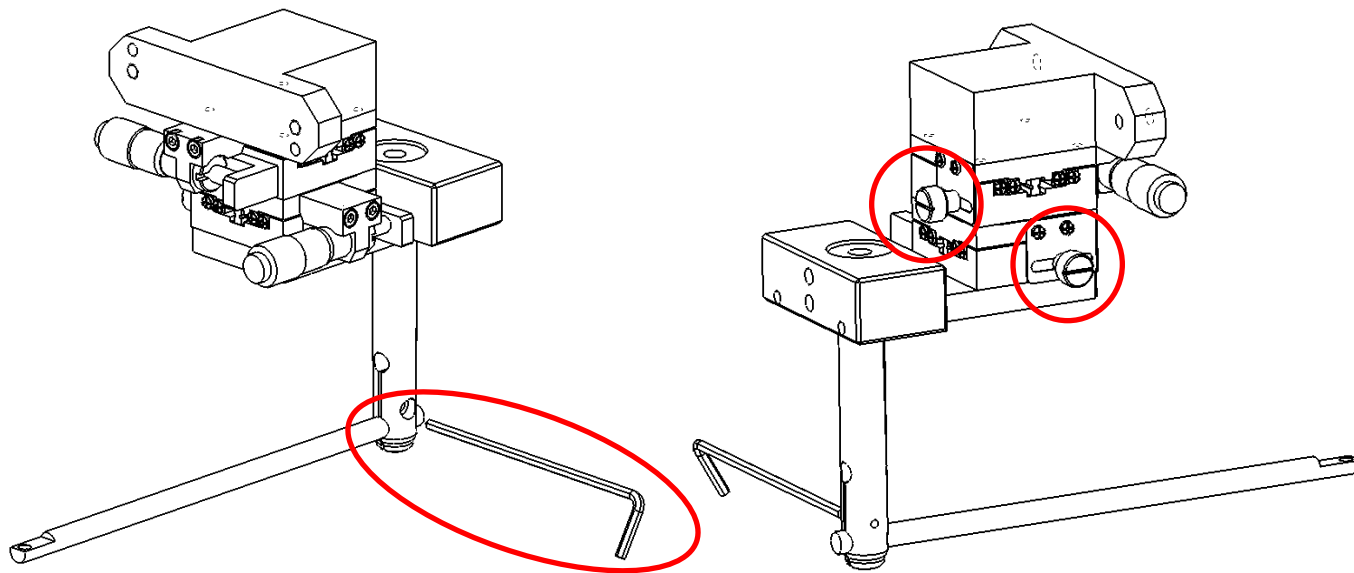
## 5.5 Method



**After fixing  $\Theta$  axis, turn the X / Y head one more time  
until the highest signal is shown on the screen of A scan window.**



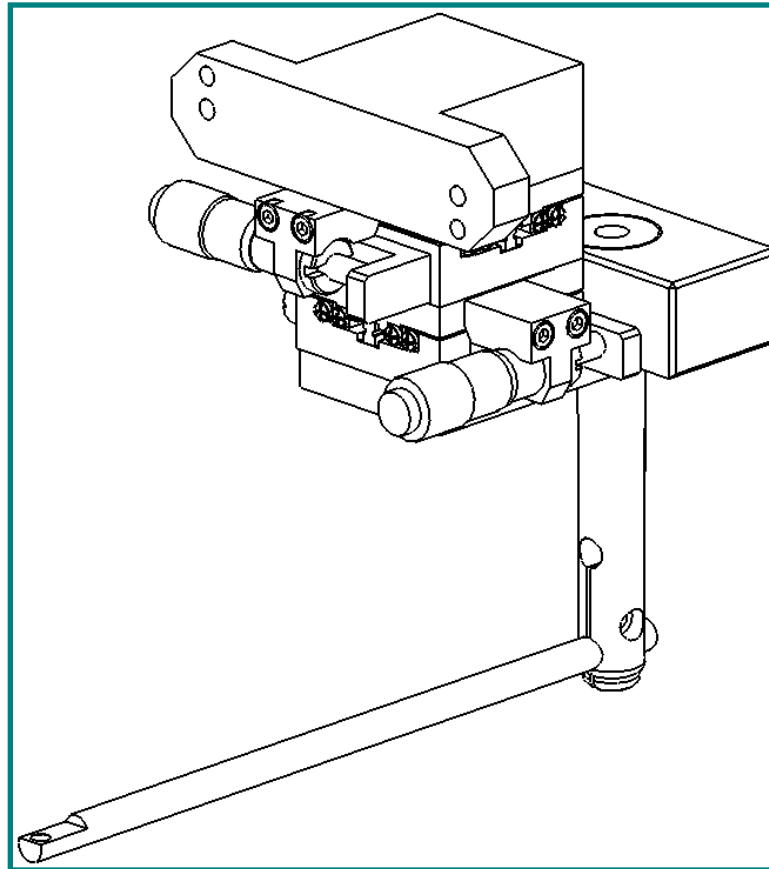
## 5.6 Method



**Fix all the fastener anticlockwise with the tool and your hand.**



## 5.7 Method



**Use it after all the adjustment is done.**